

Engine Plant Model Development and Controller Calibration using Powertrain BlocksetTM

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Key Take-Away's

- Engine model parameterization is a very nontrivial task
- Engine controller calibration is a very non-trivial task
- MathWorks has tools to help make these two tasks more manageable





Problem Statement

- How do I use the Powertrain Blockset engine and controller models for my application so I can:
 - Design engine controls?
 - Perform fuel economy and emissions studies?
 - Create and validate dynamometer test plans?



What we'll Cover Today

- Parameterizing a Powertrain Blockset engine model
 - Workflow
 - Example: parameterizing a mapped engine model
- Calibrating a Powertrain Blockset engine controller
 - Workflow
 - Example: calibrating an engine controller





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- Model-Based Calibration Toolbox provides tools for the process:
 - Creating the Design of Experiments





- Model-Based Calibration Toolbox provides tools for the process:
 - Creating the Design of Experiments
 - Gather the data





MathWorks[®]



- Model-Based Calibration Toolbox provides tools for the process:
 - Creating the Design of Experiments
 - Gather the data
 - Fitting response surface models (RSM, statistical) to the data





- Model-Based Calibration Toolbox provides tools for the process:
 - Creating the Design of Experiments
 - Gather the data
 - Fitting response surface models
 - Developing engine performance maps from RSM's





- Model-Based Calibration Toolbox provides tools for the process:
 - Creating the Design of Experiments
 - Gather the data
 - Fitting response surface models
 - Developing engine performance maps
 - Validate the result





Launch MBC Toolbox

- From Apps tab
- From command line
 >> mbcmodel





Launch MBC Toolbox





Parameterizing a Mapped Engine Model

- Importing existing data

- Mapped engine model workflow:
 - Importing existing data

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Design





Import Data

- Inspect the data
- Look for anomalies or gaps
- Filter data to remove anomalies
- Add derived quantities and unit conversions
- Graphical views speed inspection





Parameterizing a Mapped Engine Model

- Fitting response surface models
- Mapped engine model workflow:
 - Importing existing data
 - Fitting response surface models (RSM, statistical) to the data







Fitting Models to the Data

- Generate response surface models

- Default models automatically fitted to all responses
- Inspect quality of fit
- Try out alternatives





Parameterizing a Mapped Engine Model

- Developing engine performance maps
- Mapped engine model workflow:
 - Importing existing data
 - Fitting response surface models
 - Developing engine performance maps from RSM's







- Fill tables
- Export cal tables

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- Generating look up tables

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- Fill tables

Inspect surfaces

Adjust table values in extrapolation areas

 Export to MATLAB, Excel or Cal tool





Parameterizing a Mapped Engine Model

- Export and validate result
- Mapped engine model workflow:
 - Importing existing data
 - Fitting response surface models
 - Developing engine performance maps
 - Export and validate the result







Export Tables to MATLAB

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Validate the Result

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Validate the Result

- Accuracy for 1200 sec of FTP75 sim:
 - % diff in FE was 0.31%
- Run time for 1200 sec of FTP75 sim:
 - PTBS Mapped engine model 28.4 sec
 - GT Power FRM engine model 1449 sec
 - Mapped engine model sim ~51x faster





Parameterizing a Mapped Engine Model

- Summary

- Mapped engine model workflow:
 - Importing existing data
 - Fitting response surface models (RSM, statistical) to the data
 - Developing engine performance maps from RSM's
 - Validate the result





What we'll Cover Today

- Parameterizing a Powertrain Blockset engine model
 - Workflow
 - Example: parameterizing a mapped engine model
- Calibrating a Powertrain Blockset engine controller
 - Workflow
 - Example: calibrating an engine controller









- Model-Based Calibration Toolbox provides tools for the process:
 - Creating the Design of Experiments
 - Gather the data
 - Fitting response surface models (RSM, statistical) to the data
 - Developing optimal base calibration tables
 - Export calibration to controller





- Creating the DoE

- Optimal base engine control calibration workflow:
 - Creating the Design of Experiments







Design Experiment Import Data

Fit Models

Generate Calibration





Calibrating Optimal Base Engine Control Tables - Creating the DoE

I/O of Turbocharged Direct-Injection 1.5L DOHC Engine Model with Dual-Independent Continuously Variable Cam Phasing





Calibrating Optimal Base Engine Control Tables - Creating the DoE





- Gather the data

- Optimal base engine control calibration workflow:
 - Creating the Design of Experiments ____
 - Gather the data







Design Experiment

Fit Models

Generate Calibration













- Fitting response surface models

- Optimal base engine control calibration workflow:
 - Creating the Design of Experiments
 - Gather the data
 - Fitting response surface models (RSM, statistical) to the data









Design Experiment

Generate Calibration





- Generate response surface models from data

- Default models automatically fitted to all responses
- Inspect quality of fit
- Try out alternatives





- Develop optimal base calibration tables

- Optimal base engine control calibration workflow:
 - Creating the Design of Experiments
 - Gather the data
 - Fitting response surface models
 - Developing optimal base calibration tables from RSMs



Design Experiment



Import Data









- Developing calibration tables

- Import response surface models
- Run optimizations
- Analyze tradeoffs and sensitivity
- Fill tables
- Export cal tables

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- Developing calibrations from response surface models

- Import response surface models
- Run optimizations
- Analyze tradeoffs and sensitivity
- Fill tables
- Export cal tables

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- Run optimizations
- Define objective
- Define constraints
- Determine operating point weights

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Optimization			Free variables ECP, ICP
Name	Description Appletion Point Set	Status	Operating point var None
	KIT1(ECP, ICP, LOAD, Speed) <		Item scaling off
LAM	LAM(ECP, ICP, LOAD, Speed) >		
🚹 RF1	RF1(ECP, ICP, LOAD, Speed) <=		
TEXH	TEXH(ECP, ICP, LOAD, Speed) <		
TSPEED	TSPEED(ECP, ICP, LOAD, Speed		
Data Objects	d Gradient constraint of ECP over		
mod A	Gradient constraint of ICP over (
jj=a			
(1=13)(y) <		>	
Variable Optimization	n Point Set		
Dicuonary		_	
Number of	runs: 1 Vector display format: Expanded vertically	~	
Free Variat	les	Fixed Variables	
Tables Variable:	ECP ICP	Variable: BSFC_w LOAD	Speed
values:	155 - 155 -	values: 155 - 155	- 155 -
	2.343 0.139	1 (1) 35.2 0.	275 750
(2)	10.095 0.609	(2) 3.4 0.	275 1053.571
(3)	19.03 1.228	(3) 3.2 (1.35 1053.571
(4)	18.574 1.246	(4) 5.5 0.	0.5 1053.571
	19.303 1.852	(6) 0.2 0.	575 1053.571
Data Sets (7)	15.673 4.692	(7) 0.1 (0.65 1053.571
- (8)	1.495 0.125	(8) 1.1	0.2 1357.143
✓ → (9)	13.403 0.747	(9) 1.8 0.	275 1357.143
Ready			



How to calculate the weights for a sum optimization Use MATLAB to calculate weights for a drive cycle



0

Speed

Torque



- Run optimizations





- Analyze tradeoffs and sensitivity

- Evaluate local sensitivity
- Determine if tradeoffs are needed





- Fill tables

- Inspect surfaces
- Export to MATLAB, Excel or Cal tool

			750	4050 574	1057.110	1000 744	4004.000	0007.057	0574 400	0075	0470 574	0.000.4.00	0705 744	1000.000			
cesses	Tables	LO \ Sp	750	1053.571	1357.143	1660.714	1964.286	2267.857	2571.429	2875	3178.571	3482.143	3785.714	4089.286	Table Details		
<u> </u>	BaseCalibrationCage_F	0.2	0.462	0.724	1.029	4.524	0.441	0.003	0.17	0.199	3.114	3.379	40 297	2.70	Table	ICP_Table	
<u>-</u>	LOAD_norm	0.275	1 270	1.694	2.042	2.492	2.004	2.575	15.034	10 925	24.046	24 709	20.542	19.05	Size	15 x 15	
Fastura	Speed_norm	0.35	2 4 9 4	1.004	1,624	2,103	4.092	12 427	26.055	20.052	21.013	21.750	20.515	20.57	Bounds	[0,50]	
eature		0.423	2.101	1.846	1.024	1 081	3.081	10.931	20.035	20.806	30.007	20.034	28.37	23.37	Y Normalizer (. LUAD_norm(LUAD)
		0.575	4 228	2 375	1.244	1,616	3,535	4 005	14.493	24.562	25.043	28.488	26.37	27.5	X Normalizer (Speed_norm	(Speed)
		0.65	6.897	5 254	2 996	1.010	2 309	2.495	4 782	16 187	15 641	21.030	26.54	34.47	Last modified	22-Jun-2016	14:04:1
		0.05	0.057	8.15	6.241	4 469	4 724	3 704	4.702	5 715	5 363	11 627	19.645	31.05	Last A	alues filled fro	-
Tradeoff		0.725	12 061	10 704	7.742	5 250	6 151	8.081	9,602	10.851	10.061	14 525	21 187	20.53	Change: 0	ntimization out	nut
-	RF1_Table	0.875	16.471	14 135	10.076	7 714	11 188	18 001	20 202	21 712	20.827	25 315	30.233	35.73	S	Sum_BSFC_Opt	timizatio
84	TAD TAD	0.075	20.536	18 755	16.873	14 534	8 255	11.14	12 / 13	14 024	10 370	23.313	28 270	32.72	t t	put using CAGE	
		1.025	24.745	23 301	21 569	18 /08	15.46	18 564	12.413	11,800	16 321	20.023	25.273	20.60	-	Viev	v Histor
timization		1.023	28.862	27.517	25.877	24.04	23.816	25 228	20.001	17.868	18 706	20.112	22.221	26.61			· mator
		1.175	32 944	31 728	30 377	29.105	28.259	27,286	27.571	25.656	26.258	26.441	27.891	20.01	Used in		
	Torque_Table	1.175	32.344	51.720	50.577	25.105	20.233	21.200	21.511	20.000	20.230	20.441	21.001	20.4	Hom		Tuno
I Objects	v	50 ~									\geq				BSFC_Trad	leoff _Optimization	Optin
A Objects		50													BSFC_Trad	leoff _Optimization	Optim
Objects		50 + 40 + 30 + 20													BBFC_Trad	leoff _Optimization	Optim
ariable		50 40 30 20 10													BBFC_Trad	eoff _Optimization	Optim
a Objects		50 40 30 20 10 0													BBFC_Trad	_Optimization	<u>Optim</u>
A Objects		50 40 30 20 10 0 .25	1.1 0.95											4392,8571	BBFC_Trad	_Optimization	Optimi
A Objects		50 40 30 20 10 0 .25	1.1 0.95	0.8	0.65	0.5 0.35			1357 1429	1964.2857	2571.4286	3178.5714	3785.7143	4392.8571	BSFC_Trad	_Optimization	Optimi







- Export and validate the result
- Optimal base engine control calibration workflow:
 - Creating the Design of Experiments
 - Gather the data
 - Fitting response surface models
 - Developing optimal base calibrations

Export calibration to controller







Export Tables to Calibration Tool

Kport Calibration Data	_		×
Calibration items in the CAGE project BaseCalibratio	onCage_Final	:	
ltem	Туре		
BSFC_Table	2D table		~
ECP_Table	2D table		
CP_Table	2D table		
KIT1_Table	2D table		
LAM_Table	2D table		
LOAD_norm	Normalize	r	
RF1_Table	2D table		
SA_Table	2D table		
Speed_norm	Normalize	r	
TAP_Table	2D table		
TEXH_Table	2D table		
TSPEED_Table	2D table		
Torque Table	2D table		× 1
Select all by type:			
✓ 2D tables			
1D tables			
Normalizers			
Scalar constants			
Export to: INCA DCM file			
	ок	Car	ncel





- Summary

- Optimal base engine control calibration workflow:
 - Creating the Design of Experiments
 - Gather the data
 - Fitting response surface models
 - Developing optimal base calibrations
 - Export calibration to controller





Key Take-Away's

- Engine model parameterization is a very nontrivial task
- Engine controller calibration is a very non-trivial task
- MathWorks has tools to help make these two tasks more manageable





Contact us to Learn More

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Q & A

