

Praktikum MATLAB®/Simulink® I

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Author Information

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Course Details

Description

This is an introductory course for MATLAB/Simulink for control engineering students. The problems solved within this course using MATLAB/Simulink are simple modelling and control synthesis tasks.

Course Contents

Week 1

- Topic
 - General introduction to MATLAB
 - Basic commands
 - Calculus
 - Matrix operations
 - Vector operations
- Materials
 - Pework reading
 - Preparatory homework
 - Problem set for lab class
 - Solutions

Week 2

- Topic
 - MATLAB files
 - Graphs in MATLAB
 - Debugger
- Materials

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- Prework reading
- Preparatory homework
- Problem set for lab class
- Solutions

Week 3

- Topic
 - Introduction to differential equations
 - Solving differential equations with MATLAB
- Materials
 - Prework reading
 - Preparatory homework
 - Problem set for lab class
 - Template MATLAB files for tasks
 - Solutions

Week 4

- Topic
 - Introduction to helicopter model
 - Parameters and units
 - Additional important commands
- Materials
 - Prework reading
 - Preparatory homework
 - Problem set for lab class
 - Template MATLAB files for tasks
 - Solutions

Week 4

- Topic
 - Introduction to helicopter model
 - Parameters and units
 - Additional important commands
 - System description (plant model)
 - Analysis of controlled system
 - Controller design
- Materials

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- Prework reading
- Preparatory homework
- Problem set for lab class
- Template MATLAB files for tasks
- Solutions

Week 5

- Topic
 - Short introduction to Simulink
 - Fan control with Simulink
 - Helicopter model control with Simulink
- Materials
 - Prework reading
 - Preparatory homework
 - Problem set for lab class
 - Template MATLAB files for tasks
 - Solutions

Week 6

- Topic
 - Root locus analysis
 - SISO Design Tool
 - System analysis and parameter manipulation
- Materials
 - Prework reading
 - Preparatory homework
 - Problem set for lab class
 - Template MATLAB files for tasks
 - Solutions

Reading

[1] **Prof. Dr.-Ing. J. Adamy**

Systemdynamik und Regelungstechnik II

TU-Darmstadt: Institut für Automatisierungstechnik und Mechatronik, 2012

[2] **Prof. Dr.-Ing. U. Konigorski**

Systemdynamik und Regelungstechnik I

TU-Darmstadt: Institut für Automatisierungstechnik und Mechatronik, WS 2012/2013

[3] **W. D. Pietruszka**

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MATLAB und Simulink in der Ingenieurspraxis; Modellbildung, Berechnung und Simulation

Wiesbaden: Teubner, 2. Aufl. 2006

[4] **Stoer, J. und Burlisch, R.**

Numerische Mathematik 2, Springer, 2005

Links

Praktikum MATLAB/Simulink I

<http://www.rtm.tu->

[darmstadt.de/rtm_lehre/praktika_3/rtm_lehre_praktikum_matlab_1/index.de.jsp](http://www.rtm.tu-darmstadt.de/rtm_lehre/praktika_3/rtm_lehre_praktikum_matlab_1/index.de.jsp)



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