Tips and Tricks for Image Processing and Computer Vision Code Generation

Image processing algorithms may require some special consideration when used with MATLAB Coder and computer vision algorithms. Image algorithms tend to be bound by data bandwidth (as opposed to computational bandwidth). In addition, data structures with the generated code may not match those in your existing code base.

This document is designed to offer simple but effective MATLAB Coder tips and tricks that address your specific goals for image processing algorithms. It is intended to complement the <u>Quick Start Guide for</u> <u>MATLAB Coder</u>, which includes:

- MATLAB Coder Tips and Tricks
- Preparing MATLAB Code for MATLAB Coder
- Generating C Code with MATLAB Coder
- Accelerating MATLAB Code with MATLAB Coder

Table of Contents

Common Problems Before You Begin Tips and Tricks Improving Performance Unit Test Framework with MATLAB Coder MATLAB Visualization from Visual Studio and Eclipse Converting nested functions into sub functions Passing Structures by Reference Appendix A: Image Processing Toolbox Code Generation Details Appendix B: Suggested Function Replacements for Unsupported Functions



Common Problems

Data Alignment

MATLAB structures its matrices (and thus, its images) in a column major format. Most external image processing vendors tend to favor a row major format.

Example of MATLAB organized image/pixel data as **column major**:

2	5	8	11	14
3	6	9	12	15

This data is then not ordered properly when interfacing with row major functions:



Example of image / pixel data after transposing to row major:

2	3
5	6
8	9
11	12
14	15

The data is correctly ordered when interfacing to row major functions.

This is something users need to be aware of if they are:

- Integrating with external libraries (e.g., OpenCV)
- Interfacing with external hardware (e.g., CMOS image sensor)

When developing software, careful consideration is needed in order to minimize the need for unnecessary transposes and data copies.

Data Structures

When using variable sized arrays, MATLAB Coder may use data structures as a container for an image. Understanding these data structures as you integrate generated code with your existing code/libraries will help you develop more efficient algorithms.



```
typedef struct emxArray_real_T
{
    double *data;
    int *size;
    int allocatedSize;
    int numDimensions;
    boolean_T canFreeData;
} emxArray_real_T;
```

Color Representation

Color images can be represented in a variety of formats in MATLAB, but those formats may not agree with external code and or devices, again requiring special care. For instance, OpenCV uses a BGR color format, while MATLAB opts for RGB. Minimizing the interaction between the two libraries should increase performance.

Before You Begin

Determine Code Generation Goals

The first step is to determine your code generation goals. Three possible choices exist:

- Create C code combined with optimized shared libraries for x86/x64 platforms running supported operating systems (Windows, Linux, and OSX). The code and libraries are performance optimized to take advantage of technologies like Intel's IPP and TBB libraries. The library components are specific for Intel and AMD architectures and the supported OS.
- Create Standalone C/C++ code that is capable of being compiled on any processor or platform. This code is typically single treaded and is not tied to any specific architecture.
- Create and Compile MEX (MATLAB executables) for acceleration in MATLAB simulations.

Prepare MATLAB Code for Code Generation

When working with image processing and computer vision algorithms for code generation, it is first necessary to prepare the MATLAB code. Here are a few general purpose steps, but for a more complete description, see the document, <u>Preparing MATLAB Code for MATLAB Coder</u>.

This section adds additional details specifically related to image processing and computer vision algorithms.

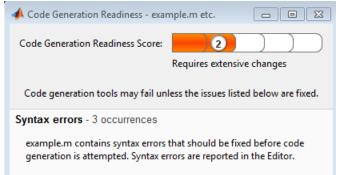
1. Insert code generation pragma



Add %#codegen comment in each MATLAB file that is meant for code generation to enable additional capabilities of the MATLAB Code Analyzer. Note: This comment can be place anywhere in the MATLAB file.



2. Exercise code readiness tool



3. Verify functions for code generation

Verify MATLAB functions that support your code generation goal. (View <u>full list of</u> <u>functions</u>.) See "Remarks and Limitations" column for details.

Name	Product	Remarks and Limitations
imfilter	Image Processing Toolbox	The input image can be either 2-D or 3-D. The value of the input argument, options, must be a compile-time constant. Generated code for this function uses a precompiled platform-specific shared library.

Functions that support code generation can do one of the following:

- Generate ANSI C *source* code (platform *independent*). Most functions do this.
- Generate precompiled platform-specific *shared library* (platform-*dependent*).

If you see "platform-specific shared library" in the <u>supported function list</u>, it means it can generate a precompiled platform-specific shared library.

- **4.** Verify Image Processing Toolbox functions that support your code generation goal. See Appendix A for code generation details.
- 5. Verify Computer Vision System Toolbox functions that support your code generation goal. View <u>list of functions</u>. Make note of the "Remarks and Limitations" column for details.



- 6. Unsupported functions require rewriting MATLAB code or calling external C libraries.
 - See section, "Leveraging External Libraries and Custom C Code."
 - See Appendix B for a list of suggested function replacements.

Tips & Tricks

Improving Performance

There are several techniques for improving the performance of your generated code. The following are a few recommendations:

- Turn off Dynamic Memory Allocation (MALLOC) and avoid functions that require MALLOC in performance critical areas if possible (i.e. loops). To disable dynamic memory allocation in the Project Settings box:
 - On the MATLAB Coder project **Build** tab, click **More settings**.
 - In the **Project Settings** dialog box **Memory** tab, under **Enable variable-sizing**, set **Dynamic memory allocation** to **Never**.
- 2. Enable parallel processing on multicore machines with OpenMP. If your target compiler supports OpenMP then use parfor to run parallel threads on a multicore machines.
- 3. Use Code Generation Metrics Report to gather statistics on the generated code. View <u>more information</u>.

/iew: Call Tree Table						
Function Name	Called By (number of call sites)	Accumulated Stack Size (bytes)	Self Stack Size (bytes)	Lines of Code	Lines	Complexity
moving_average		8	8	4	13	1
moving_average_initialize		44	0	1	4	1
moving_average_terminate		0	0	0	4	1
rtGetInf		38	34	36	43	5
rtGetInfF	rtGetInf	4	4	3	6	1
rtGetMinusInf		38	34	36	43	5
rtGetMinusInfF	rtGetMinusInf	4	4	3	6	1
rtGetNaN		44	34	36	43	5
rtGetNaNF	rtGetNaN	10	10	19	24	4
rtisInf		0	0	1	4	2
rtisinfF		0	0	1	3 4	2
rtisNaN		0	0	5	8	2
rtisNaNF		0	0	5	8	2
rt_InitInfAndNaN		44	0	7	10	1

3. Function Information [hide]

For more information on improving performance, see <u>Accelerating MATLAB Code with</u> <u>MATLAB Coder</u>.



- 4. Integrate existing C code and libraries. Often you will have existing code that you would like to leverage in MATLAB with code generation. This section shows how to integrate external code into MATLAB and to generate code that uses your existing code.
 - To integrate existing code or to preserve modifications to generated code, use coder.target.

o Here is an example of how to use coder.target

```
if coder.target('MATLAB') % runs in MATLAB
    y = algo_in_MATLAB(x);
else % used by MATLAB Coder
    y = zeros(size(x)); % Pre-define output
    coder.ceval('algo_in_c',x,y);
end
```

View more information.

• To integrate external libraries with header files, use

coder.ExternalDependency. This allows external libraries to be accessed for MATLAB simulations and to be included with code generation. Here is an example using coder.ExternalDependency:

```
function c = adder(a, b)
    coder.cinclude('adder.h');
    c = 0;
    c = coder.ceval('adder', a, b);
end
y = AdderAPI.adder(x1, x2);
```

Features of the coder.ExternalDependency class includes the following:

- Easy to use as it uses coder.ceval to execute the custom code
- Support for variable sized arrays
- Most controls are on MATLAB side and less burden on external users
- Creates build info with include paths, header file names, library names
- Converts MATLAB variables to C types and calls C function API
- Calls MATLAB function with coder.ceval
- Converts MATLAB variable to C pointer using coder.ref or coder.wref
- Scalar can be passed without any conversion

View more information.

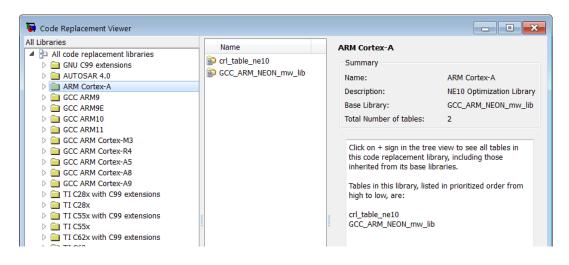


5. To take advantage of low level replacements of intrinsic operators, use Code Replacement Library (CRL). For a replacement to occur, the operator and data type arguments must match the table tale precisely. Here is the dialog tab showing the selection of some sample intrinsics.

Note: CRL requires that the input types match and see RTX.Tfl file for more details. The CRL capability also requires a license for Embedded Coder.

📣 Project	Settings							- • ×
Paths	Speed	Memory	Code Appearance	Debugging	Custom Code	I Hardware	X Toolchain	(O) All Settings
Standard	math librar	y: C89/C	90 (ANSI)			•		
Code rep	lacement lik	orary: None				▼ Custom		
	e Settings		C99 extensions					
V Test	naruware i	s the stauto:	SAR 4.0 Cortex-A					
Setting		GCC A	RM9					
Device	e Vendor	GCC A	RM9E					
Device	e Type	GCC A	RM10					
▲ Sizes		GCC A	RM11			Ŧ		

Note: Use the following command for a full list of library replacements:



Features of CRL include the following:

> RTW.viewTfl

- Replace low-level MATLAB implementations
- Limitation: does not support variable size



- Needs dedicated table entry for library replacement (uses coder.replace)
- Requires Embedded Coder

CRL example:

When targeting the ARM Cortex-A and Cortex-M, the Ne10 and CMSIS Code Replacement Library (CRL) can be used to sSupport Ne10 (ARM Cortex-A):

```
nel0_add_float_neon()
nel0_sub_float_neon()
nel0_mul_float_neon()
nel0_divc_float_neon()
```

- 6. Interface with row-major code libraries. For image processing and computer vision (IPCV) applications, the fact that MATLAB is column-major while C/C++ code is row-major can cause issues. This can occur especially when dealing with code generation (pushing MATLAB algorithms to C code) or legacy code integration (bringing legacy C code into MATLAB). Here are two approaches to deal with this:
 - Modify the existing MATLAB algorithm in such a way as to process matrix data in a transposed manner.
 - At the input and output boundaries of the algorithms, transpose the input/output matrices.

Unit Test Framework with MATLAB Coder

Users can write an extensive set of test cases for a MATLAB function using the MATLAB Unit Test Framework, capturing expected behavior, edge cases, and exceptions thrown.

This capability can be combined when you generate code for the function using MATLAB Coder. Use the Unit Test Framework with MEX-files.

View more information.

Visualization and Verification from Visual Studio and Eclipse

When developing C/C++ applications in Visual Studio and Eclipse, it can be challenging to visualize and experiment with code changes, and test and verify results.

MATLAB Engine enables you to visualize, experiment, and test C/C++ code directly from Visual Studio and Eclipse by communicating with MATLAB. This connection enables you to access MATLAB plots, toolbox functions, and scripts directly from Visual Studio and Eclipse. With this connection, you can quickly explore and test results throughout the development phase to save time and effort.



Solution Explorer Team Explorer 0			
Solution Explorer Team Explorer 0	ML_Engine_Demo (Debugging) - Micros	soft Visual Studio (Administrator)	Figure 3
Process: [9588] ML_Engine_Demo.exe Suppend Thread: [108 Solution Explorer Team Explorer (Cit+2) P = Secrit Solution ML Engine Demo (Lipro) * Const double* Lesize = engGetVariable(ep, "Liproy"); * agaussian3x3 h # Resource Files * agaussian3x3 cpp * * gaussian3x3 cpp * * gaussian3x3 cpp * * gaussian3x3 cpp * * multiplicedemo.cpp * * MLenginedemo.cpp * * * MLenginedemo.cpp * * * MLenginedemo.cpp * * * MLenginedemo.cpp * * * * MLenginedemo.cpp * * * * * * * * * * * * * * * * * * *	<u>FILE EDIT VIEW PROJECT BUI</u>	ILD <u>D</u> EBUG TEA <u>M</u> S <u>Q</u> L <u>T</u> OOLS	<u>File E</u> dit <u>V</u> iew Insert <u>T</u> ools <u>D</u> esktop <u>W</u> indow <u>H</u> elp *
Solution Explorer Value Search Solution Explorer (Crt+2) P Search Solution MLEngine Demo (1 proj. MEngine Demo Search Solution MLEngine Demo (1 proj. MEngine Demo F Electeral Dependences Menginedemo.cpp * Resource Files * Resource Files * Source Files * Source Files * Resource Files * Resource Files * Source Files * Resource Files * Costs uint2_t* Ip = static_castculnt8_t*>(mxGetData(Igray)); // Pointer to MATLAB variations to the static_castculut8_t*>(mxGetData(Igray)); // Pointer to VATLAB variations to the static_castculut8_t*>(mxGetData(Igray), mxUIHT8_CLASS, mxREF * Costs of C utput to MATLAB workspace for a * Costs 0 C implementation of a 3x3 Gaussi */ * Costs 0 C implementation of a 3x3 Gaussi */	S - O 🖄 - 🏭 💾 🥙 🤈 -	Continue - Debug - 🎜	1 🗋 🖆 🚽 🦫 🔍 🔍 🥙 🧶 🖌 - 🗔 🗉 🗉 🔲
Global Scope Search Solution MLEngine Demo (Lirl+) P - T - T - T - T - T - T - T - T	Process: [9588] ML_Engine_Demo.exe	- E Suspend - E Thread: [108	
<pre>* Custom C implementation of a 3x3 Gaussi */ fngaussian3x3(Ip, I_sizep, outputp); // c Solution Explorer Team Explorer Locals ** * hInstance 0x000000013f9c0000 (unused= HINST, * Autos Locals Watch 1</pre>	Solution Explorer Solution Explorer Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Search Solution 'ML_Engine_Demo Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraint of the system Image: Constraintof the system </td <td><pre>gaussian3x3.cpp MLenginedemool (Global Scope) * - Call prebuilt MA * - Generate C code */ engEvalString(ep, "Thr * Retrieve results frr * - Data marshalling */ Igray = engGetVariable const uint8_t* Ip = st I_size = engGetVariable const double* I_sizep i mxArray* output = mxCr</pre></td> <td><pre>(ep, "Igray"); // Pointer to MATLAB varie atic_cast</pre>(mxGetData(Igray)); // Pointer to MATLAB varie le(ep, "IgraySize"); // Pointer in C variable le(ep, "IgraySize"); // Pointer in C variable let(ast(mxGetData(I_size)); // Pointer in C variable</td>	<pre>gaussian3x3.cpp MLenginedemool (Global Scope) * - Call prebuilt MA * - Generate C code */ engEvalString(ep, "Thr * Retrieve results frr * - Data marshalling */ Igray = engGetVariable const uint8_t* Ip = st I_size = engGetVariable const double* I_sizep i mxArray* output = mxCr</pre>	<pre>(ep, "Igray"); // Pointer to MATLAB varie atic_cast</pre> (mxGetData(Igray)); // Pointer to MATLAB varie le(ep, "IgraySize"); // Pointer in C variable le(ep, "IgraySize"); // Pointer in C variable let(ast(mxGetData(I_size)); // Pointer in C variable
eady 0 50 100 150 200 250 300	Locals Name Value	<pre>* Custom C implementa */ fngaussian3x3(Ip, I_si // Push C output to MAi engPutVariable(ep, "ou 100 % < 4</pre>	tion of a 3x3 Gaussi zep, outputp); // C TLAB workspace for a tput", output); m: Debug points Command Window
	Ready		0 50 100 150 200 250 300

For more information, see documentation for <u>MATLAB Engine API for C, C++, and Fortran</u>.

Converting Nested Functions into Sub-Functions

Nested functions are not yet supported in MATLAB Coder (as of R2014a). Here're a workaround to make nested functions codegen ready:

- 1. Move the nested function to its own sub-function
- 2. Pass any data used by the nested function as inputs to the new sub-function
- 3. Return any data needed by the main function back as an output of the sub-function

Passing Structures by Reference

Depending upon the MATLAB code and/or the configuration of MATLAB Coder, generated code will either pass by value or pass by reference. When a function has one or two simple scalar values, passing by value is usually more efficient. However, when function arguments are larger, passing by reference is more efficient.



MATLAB Coder will generate both idioms and the result will depend on when the MATLAB function includes:

- An input argument
- An output argument
- An input/output argument.

The code also differs for:

- MEX targets
- Standalone code

Here is the MATLAB code used to test each case.

Input only	Output only	Input and Output	
<pre>function y = strin(s)</pre>	<pre>function s = strout(x)</pre>	<pre>function [y,s] = strinout(x,s)</pre>	
y = s.f;	s.f = x;	y = x + sum(s.f);	

1. PassStructByReference option

Starting in R2013a, a "Pass Structure by Reference" option was introduced.

It only applied to input structures in R2013a, and was later extended to apply to output structures in R2013b.

This option is only applicable to standalone code. There is no option to alter the generated MEX code.

Note: The default from the user interface is cfg.PassStructByReference=true for R2013b and R2014a, but from the command line the default is

cfg.PassStructByReference=false, as shown in the following tables by "default prj" and "default cfg" respectively.

2. Structure is an input

function y = strin(s)
y = s.f;

Stand-alone C code:

	cfg.PassStructByReference=false
R2013a (default)	void strin(const struct_T s, real_T y[4])
R2013b (default cfg)	void strin(const struct_T s, double y[4])
R2014a (default cfg)	void strin(const struct0_T s, double y[4])

	cfg.PassStructByReference=true;
R2013a	<pre>void strin(const struct_T *s, real_T y[4])</pre>
R2013b (default prj)	void strin(const struct_T *s, double y[4])
R2014a (default prj)	void strin(const struct0_T *s, double y[4])



MEX code:

	cfg.PassStructByReference not applicable	
R2013a	void strin(const struct_T *s, real_T y[4])	
R2013b	void strin(const emlrtStack *sp, const struct_T *s, real_T y[4])	
R2014a	void strin(const struct0_T *s, real_T y[4])	

3. Structure is an output

function s = strout(x)
s.f = x;

Stand-alone C code:

	cfg.PassStructByReference=false
R2013a (default)	struct_T strout(const real_T x[4])
R2013b (default cfg)	struct_T strout(const double x[4])
R2014a (default cfg)	struct0_T strout(const double x[4])

	cfg.PassStructByReference=true;
R2013a	<pre>struct_T strout(const real_T x[4])</pre>
R2013b (default prj)	void strout(const double x[4], struct_T *s)
R2014a (default prj)	void strout(const double x[4], struct0_T *s)

Default from the user interface is <code>cfg.PassStructByReference=true</code> for R2013b and R2014a, but from the command line the default is

cfg.PassStructByReference=false.

MEX code:

	cfg.PassStructByReference not applicable		
R2013a	<pre>struct_T strout(const real_T x[4])</pre>		
R2013b	<pre>void strout(const emlrtStack *sp, const real_T x[4], struct_T *s)</pre>		
R2014a	<pre>void strout(const real_T x[4], struct0_T *s)</pre>		

4. Structure is an input and an output

function [y,s] = strinout(x,s)
y = x + sum(s.f);

Stand-alone C code:

	cfg.PassStructByReference=false
R2013a (default)	<pre>void strinout(const real_T x[4], const struct_T *s, real_T y[4])</pre>
R2013b (default cfg)	void strinout(const double x[4], const struct_T *s, double y[4])
R2014a (default cfg)	void strinout(const double x[4], const struct0_T *s, double y[4])

	cfg.PassStructByReference=true;
R2013a	Same as false
R2013b (default prj)	Same as false
R2014a (default prj)	Same as false



Default from the user interface is <code>cfg.PassStructByReference=true</code> for R2013b and R2014a, but from the command line the default is

cfg.PassStructByReference=false.

MEX code:

	cfg.PassStructByReference not applicable		
R2013a	<pre>void strinout(const real_T x[4], const struct_T *s, real_T y[4])</pre>		
R2013b	void strinout(const emlrtStack *sp, const real_T x[4], const struct_T *s, real_T y[4])		
R2014a	<pre>void strinout(const real_T x[4], const struct0_T *s, real_T y[4])</pre>		

Appendix A:

Image Processing Toolbox Code Generation Details:

Function	Generates standalone C code (any target)	Generates standalone C code using platform- specific shared library (applies when hardware is set to "MATLAB Host Computer")	Requires dynamic memory allocation support	Requires enabling variable sizing support	Comments/limitations
affine2d	14a	NA	No	No	
bwdist	No	14b	No	No	
bweuler	15a	15a	No	Yes	
bwlabel	15a	NA	Yes	Yes	
bwlookup	14b	12b	No	Yes	
bwmorph	14b	12b	No	No	
bwpack	No	14a	No	No	
bwperim	15a	15a	No	Yes	
bwselect	15a	14a	No	Yes	
bwtracebound ary	14b	NA	Yes	Yes	
bwunpack	No	14a	No*	No*	* Dynamic memory allocation is not required provided M is a compile- time constants.
conndef	13a	NA	No	No	



edge	15a	14a	No*	Yes	* Dynamic memory
cage	154	140	NO	163	allocation is not required
					provided THRESH and
					SIGMA are compile-time
					constants.
fitgeotrans	14b	NA	No	No	constants.
fspecial	Pre-12b [%]	NA	No*	Yes	* Dunamia mamany
тэрестат	Pre-120	NA	NO .	res	* Dynamic memory allocation is not required
					provided HSIZE, RADIUS,
					LEN and THETA are
					compile-time constants.
					Prior to 14b, this function generated constant-
					folded C code. In 14b, the
					function started
getrangefrom	14a	NA	No	No	generating C code.
class	140	NA NA	NO	NO	
histeq	No	14b	No*	No*	* Dynamic memory
					allocation and variable-
					sizing support is not
					required provided N is a
					compile-time constant.
hsv2rgb^	14b	NA	No	No	
im2uint8	15a	14a	No	No	
im2uint16	No	14a	No	No	
im2int16	No	14a	No	No	
im2single	14a	NA	No	No	
im2double^	14a	NA	No	No	
imadjust	No	14b	No	No	
imbothat	14b	14a	No	Yes	
imclearborde	15a	14b	No	No	
r	100	2.12			
imclose	14b	14a	No	Yes	
imcomplement	13a	NA	No	No	
TWCOWDICWCIIC	120	INA	INU		
imdilate	14b	14a	No	Yes	
imerode					
TILETONE	14b	14a	No	Yes	

Accelerating the pace of engineering and science

imextendedma	15a	14a	No	Yes	
X	150	140	NO	103	
imextendedmi	15a	14a	No	Yes	
n	134	140	NO	163	
imfill	15a	13a	No	Yes	
	139	154	NO	Tes	
imfilter	14b	14a	No	Yes	
imhist	15a	14a	No*	No*	* Both dynamic memory
					allocation and variable-
					sizing support is not
					required provided N, the
					number of bins is a
					compile-time constant.
imhmax	15a	13a	No	Yes	
imhmin	15a	13a	No	Yes	
			_		
imlincomb	No	14b			
	NO	140			
imopen	14b	14a	No	Yes	
Imopen	140	140	NO	163	
imquantize	14b	NA	No	No	
imreconstruc	15a	13a	No	Yes	
t			_		
imref2d	14a	NA	No	No	
imref3d	14a	NA	No	Yes	
imregionalma	15a	13a	No	Yes	
X					
imregionalmi	15a	13a	No	Yes	
n imtophat	14b	145	No	Voc	
_	14b	14a	No	Yes	* Dun and is used in the
imwarp	15a	14a	No*	Yes	* Dynamic memory
					allocation is not required
					provided TFORM is a compile-time constant.
intlut	No	14b	No	No	
iptcheckconn	13a	145 NA	No	No	
iptcheckmap	13a 14b	NA	No	No	
label2rgb					
τανετζτζυ	Pre-12b	NA	No	No	

Accelerating the pace of engineering and science

mean2	13b	NA	No	No	
medfilt2	15a	14b	No*	Yes	* Dynamic memory allocation is not required provided [M N], the neighborhood size is a compile-time constant.
multithresh	15a	14b	No*	Yes	* Dynamic memory allocation is not required provided the number of thresholds, N is a compile-time constant.
ordfilt2	15a	14b	No	Yes	
padarray	13a	NA	No*	No*	* Both dynamic memory allocation and variable- sizing support is not required provided PADSIZE is a compile-time constant.
projective2d	14a	NA	No	No	
rgb2gray^	14b	NA	No	No	
rgb2hsv^	14b	NA	No	No	
rgb2ycbcr	No	14b	No	No	
regionprops	15a	15a	Yes	Yes	
strel	14a	NA	No	No	
stretchlim	15a	14b	No	No	
watershed	15a	15a	Yes	Yes	
ycbcr2rgb	No	14b	No	No	
^Indicates that the function is in base MATLAB.					
* Indicates that the function supports a feature provided certain conditions in the Comments/Limita tions section are met.					



% Indicates an			
enhancement to			
the generated			
code.			

Appendix B:

Suggested Function Replacements for Unsupported Functions

MATLAB function	Suggested replacement	Comments
imcrop	vision.ImagePadder	<pre>imcrop not supported for code generation</pre>
imrotate	vision.GeometricRotato r	imrotate not supported for code generation
graythresh	multithresh	<pre>thresh = graythresh(img);</pre>
		can be replaced by:
		<pre>thresh = ultithresh(img,1);</pre>
graythresh	vision.Autothresholder	<pre>bw = im2bw(img,graythresh(img))</pre>
		can be replaced by
		AT = vision.Autothresholder;
		im2bw takes threshold input on [0,1]. You may need to
		<pre>recast img as type double or to re-scale thresh to</pre>
		match type of img.
im2bw		<pre>im2bw(img,thresh)</pre>
		can be replaced by
		<pre>bw = img > thresh;</pre>



		<pre>im2bw takes threshold input on [0,1]. You may need to recast img as type double or to re-scale thresh to match type of img.</pre>
im2bw		In R2014b and later, use imquantize in place of im2bw
imshow		Consider removing visualizations for codegen
regionprops	vision.BlobAnalysis	
labelmatrix	vision.ConnectedCompon entLabeler	
imread		Consider passing image (matrix) in directly instead of using imread
imread	vision.VideoFileReader	Reads in images (.jpg, .bmp only), video, and audio
imread	Use OpenCV calls (i.e. cv::imread) in a C++ environment.	
bwlabel	vision.ConnectedCompon entLabeler	
bwareaperim	vision.BlobAnalysis	
bwareaopen	vision.MorphologicalOp en	
bwareaopen	vision.ConnectedCompon entLabeler in conjunction with vision.Autothresholder	
bwareaopen	vision.BlobAnalysis	

